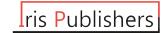
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# Stiffness of Three-Phase Concentric Composite Solids

## **Victor Birman\***

Department of Mechanical and Aerospace Engineering, Missouri University of Science and Technology, Rolla, Missouri, USA

\*Corresponding author: Victor Birman, Department of Mechanical and Aerospace Engineering, Missouri University of Science and Technology, Rolla, Missouri, USA.

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### Introduction

There are numerous examples of three-phase concentric composites, including coated fiber-reinforced materials and syntactic foams. The stiffness of such three-phase materials is usually investigated by micromechanical methods specified for this particular case. For example, Luo and Weng presented solutions for three-phase concentric spheres [1] and for three-phase concentric cylinders models [2] of an inclusion, a coating ("intermediate matrix"), and a matrix using the Mori-Tanaka method. Among numerous studies of three-phase or multi-phase composites one can mention [3-6].

The present approach employs a combination of two-phase matrix-inclusion models to determine the stiffness of a three-phase solid. The advantage of the proposed method is its simplicity, i.e. a reduction of the three-phase composite micromechanics to a superposition of available two-phase solutions, without a need in additional analytical procedures. This method is also universal and can be applied with any micromechanical theory available for two-phase composites.

Keywords: Composite materials; Micromechanics; Coated fibers; Syntactic foams

# **Analysis**

Consider a composite with two-phase concentric inclusions uniformly distributed over the volume (Figure 1). Our goal is to evaluate the stiffness of such three-phase material given the engi neering constants of each phase. The solution is obtained by the following superposition of two-phase composite models represented in Figure 1 for spherical inclusions.

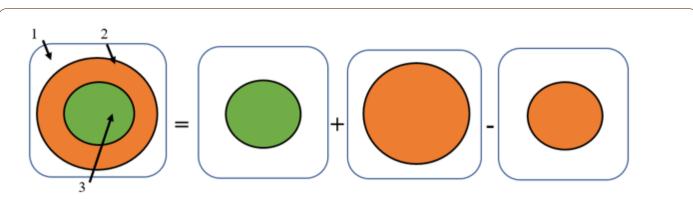


Figure 1: Approach to the evaluation of the stiffness of a three-phase concentric composite solid on the example of spherical inclusions.

The stiffness tensor is found as the following combination of the stiffness tensors of two-phase composites:

$$L = L_{13}(\Omega_3) + L_{12}(\Omega_2 + \Omega_3) - L_{12}(\Omega_3)$$
 (1)

where 1, 2 and 3 refer to materials of matrix (material 1 in Figure 1), and inclusions 2 and 3, respectively, and  $\Omega i$  is the volume (space) occupied by the i-th material. Accordingly,  $L_{13}(\Omega_3)$  is the tensor of stiffness of a two-phase composite where material 3 occupies the space of material 3 in the three-phase model,  $L_{12}(\Omega_2 + \Omega_3)$  is the tensor of a composite where material 2 occupies the space of materials 2 and 3, and  $L_{12}(\Omega_3)$  is the tensor of a composite where material 2 occupies the space  $\Omega_3$ . Note that the approach demonstrated in Figure 1 is applicable to more general cases of ellipsoidal concentric inclusions or coated fibers. The interaction between the inclusions is accounted for in two-phase micromechanical models.

As an example of the application of the method described above, the tensors of stiffness of two-phase materials in the right side of eqn. (1) can be evaluated by the Mori-Tanaka method using the solution by Benveniste [7]:

$$L_{mi} = L_m + V_i [L_i - L_m) T ] [V_m I + V_i T]^{-1}$$
 (2)

where subscripts "m" and "i" refer to the matrix and inclusions, respectively,  $V_i$  and  $V_m$  are the volume fractions of the inclusions and matrix,  $\boldsymbol{I}$  is the unit tensor and  $\boldsymbol{T}$  is the strain concentration tensor of dilute inclusions:

$$T = [I + SL_m^{-1}(L_i - L_m)]^{-1}$$
 (3)

In eqn. (3), S is the fourth order Eshelby's tensor. In the case of spherical inclusions, explicit formulas for engineering constants are available.

Another example of solutions employing eqn. (1) can also be obtained in the case where inclusions are cylindrical and randomly oriented. The comprehensive solution can be derived using the well-known Tsai-Pagano method based on the properties of a unidirectional composite that are obtained by the Tsai-Halpin method. The solution can also be obtained by the method of Christensen and Waals [8,9]. In particular, a very simple solution is obtained if the inclusion volume fraction is below 20%. While the Poisson ratio is adequately approximated by the rule of mixtures, the modulus of elasticity of the material with 3-D randomly oriented fibers is obtained by

$$E = \frac{V_f}{6} E_f + [1 + (1 + v_m)V_f]E_m$$
 (4)

where the subscript "f" refers to the fibers, E,  $E_f$  and  $E_m$  are the moduli of elasticity of the composite, fiber and matrix, respectively, and vm is the matrix Poisson ratio. Notably, the present equation

does not account for the fiber aspect ratio; accordingly, it may not be suitable for short fibers where this ratio has a noticeable effect on the stiffness.

The examples of micromechanical methods suitable for using with the proposed two-phase superposition approach can be extended to any analytical theory, such as self-consistent, Ponte Castaneda-Willis and Kuster-Toksoz methods, etc. Numerical examples and a comparison with available solutions and experimental data will be included in an extended article.

In conclusion, the present method enables to approach the analysis of the stiffness of three-phase and, with the necessary expansion, multi-phase concentric composite solids using available micromechanical methods for two-phase composites. Such approach can significantly simplify the analysis of relevant composite materials.

# Acknowledgement

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# **Conflict of Interest**

No conflict of interest.

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